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Ecole doctorale
Sciences Pour
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Optimization of Prestressed Concrete Bridges

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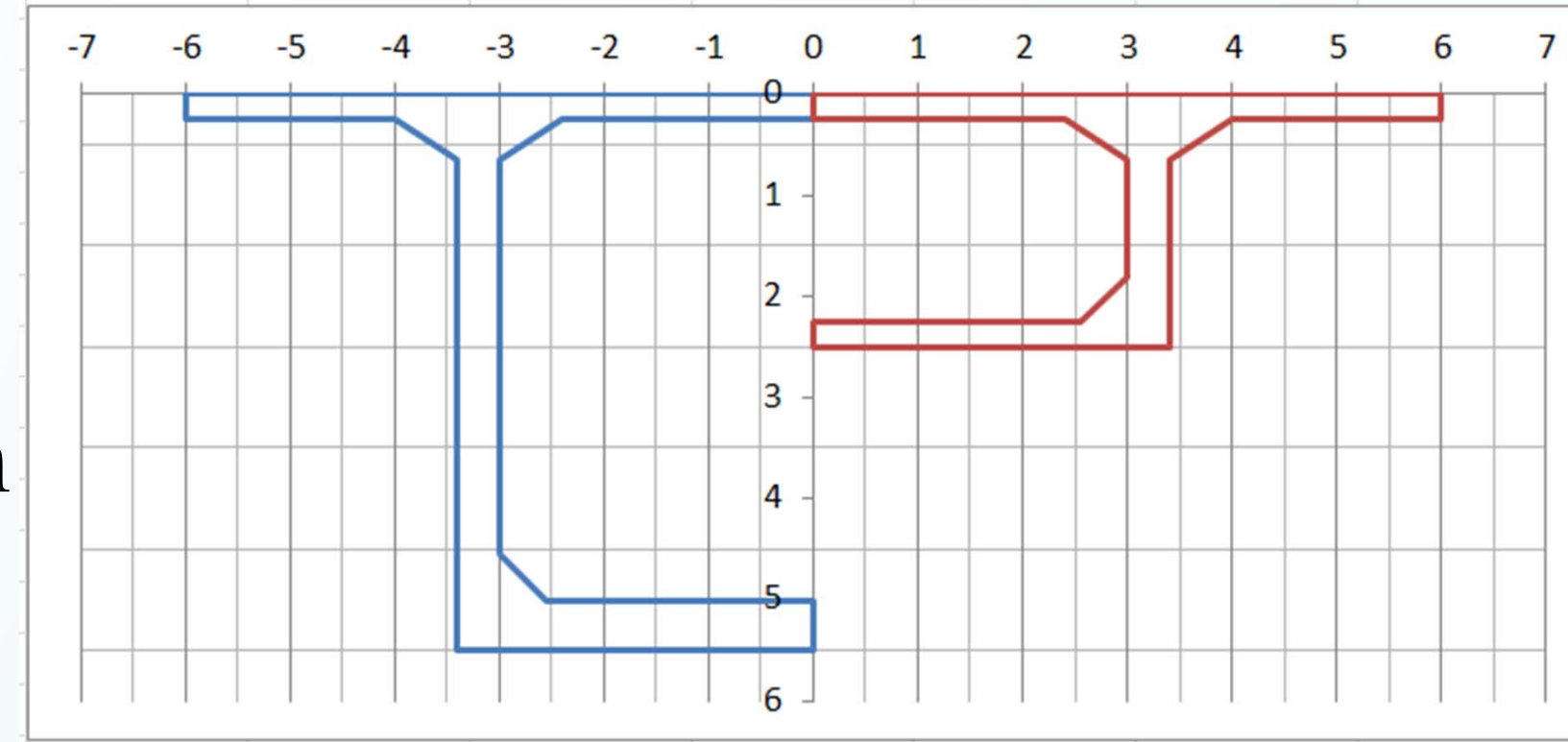


Target

Optimization of prestressed concrete bridges aiming to minimize the cost while maintaining the bridge's functionality, has long occupied the mind of many researchers.

Objectives set for this study:

- Resolution of a multi-span beam with variable stiffness using a new developed analytical approach
- Introducing the new pivot rule in fully and partially prestressed concrete sections (SLS & ULS)
- Develop new methods of optimization for the design of prestressed concrete Bridges



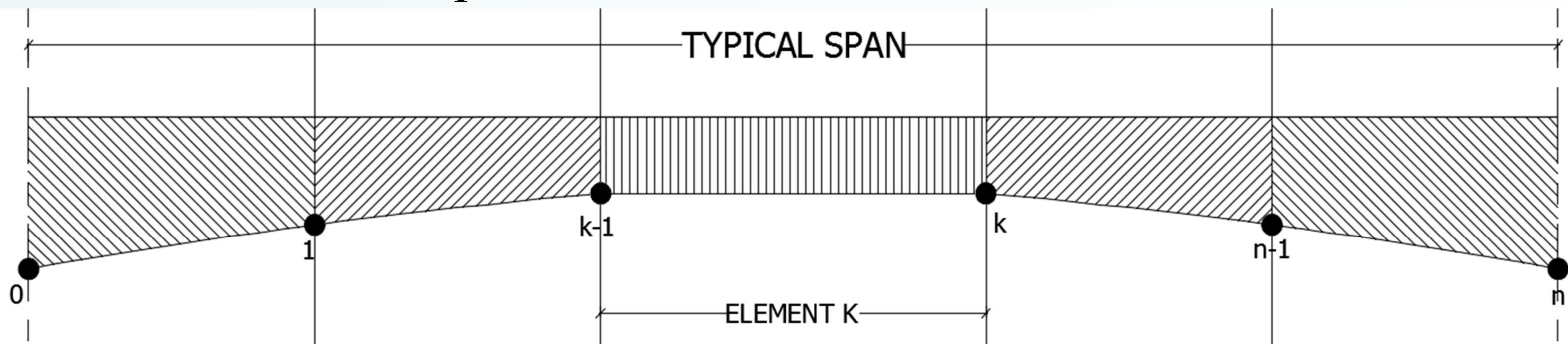
Methodology

New "Transfer Matrix" Method For Continuous Beams :

$$S_n = \int_0^l \frac{x^n}{l^n} \frac{dx}{EI}$$

Main principles behind this Method:

1. Use the integral S_n for the calculation of the Mechanical Constants (a, b & c) and the Rotations δ_i of the 3-Moment equation.
2. Choose the proper segmentation along the beam. ("Beam Meshing")
3. Convert the S_n expression into a "Matrix"



$$S_{k,n} = S_{k-1,n} + \sum_{j=0}^n \binom{n}{j} \beta_K^n \alpha_K^{n-j} (1 - \alpha_K)^j \times I_{k,j}$$

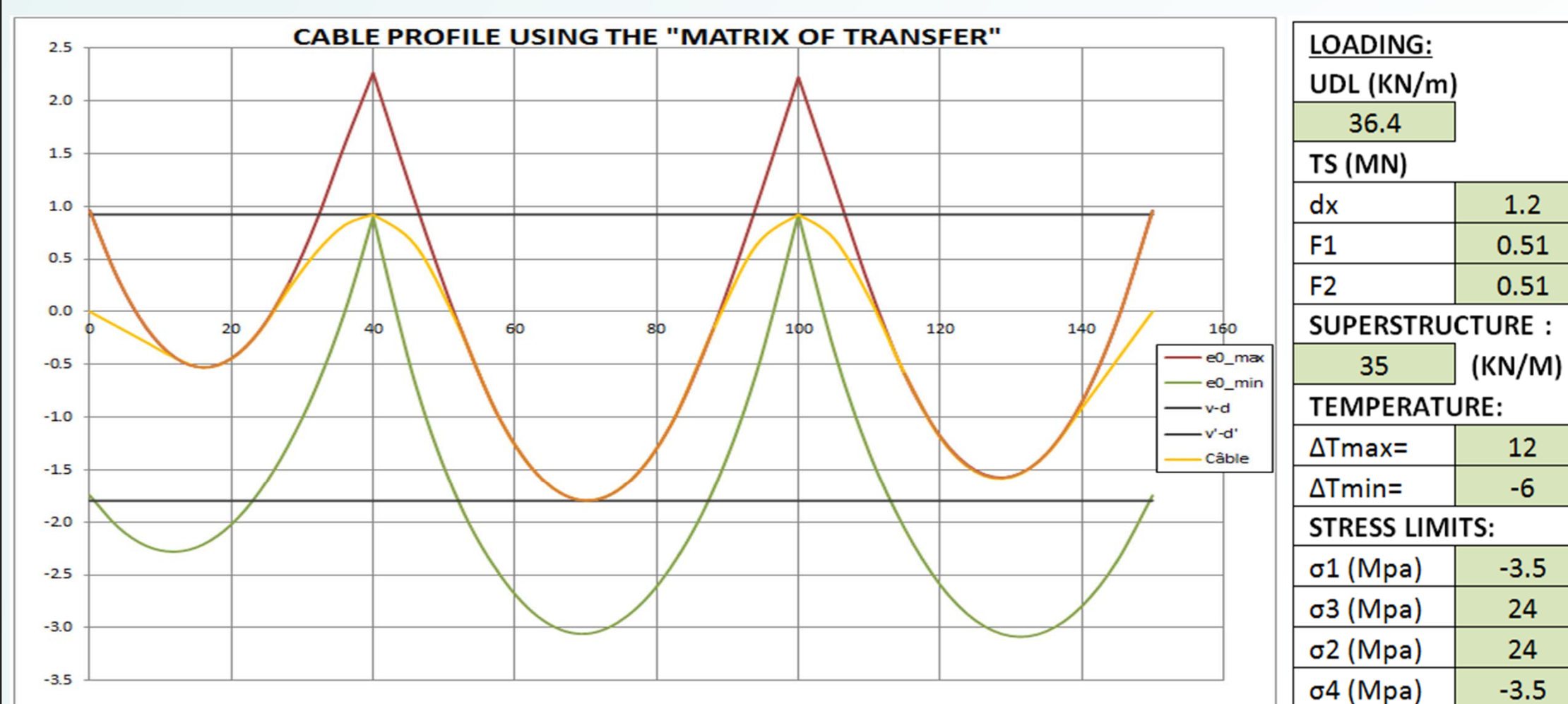
$$\frac{x_k^n}{l^n} = \beta_K^n$$

$$\frac{x_{k-1}}{x_k} = \alpha_K$$

$$\begin{bmatrix} S_{k,0} \\ S_{k,1} \\ S_{k,2} \\ S_{k,3} \end{bmatrix} = \begin{bmatrix} S_{k-1,0} \\ S_{k-1,1} \\ S_{k-1,2} \\ S_{k-1,3} \end{bmatrix} + A(\beta_K, \alpha_K) \begin{bmatrix} I_{k,0} \\ I_{k,1} \\ I_{k,2} \\ I_{k,3} \end{bmatrix}$$

Results

Multi-Span PT beam using the "Matrix of Transfer:



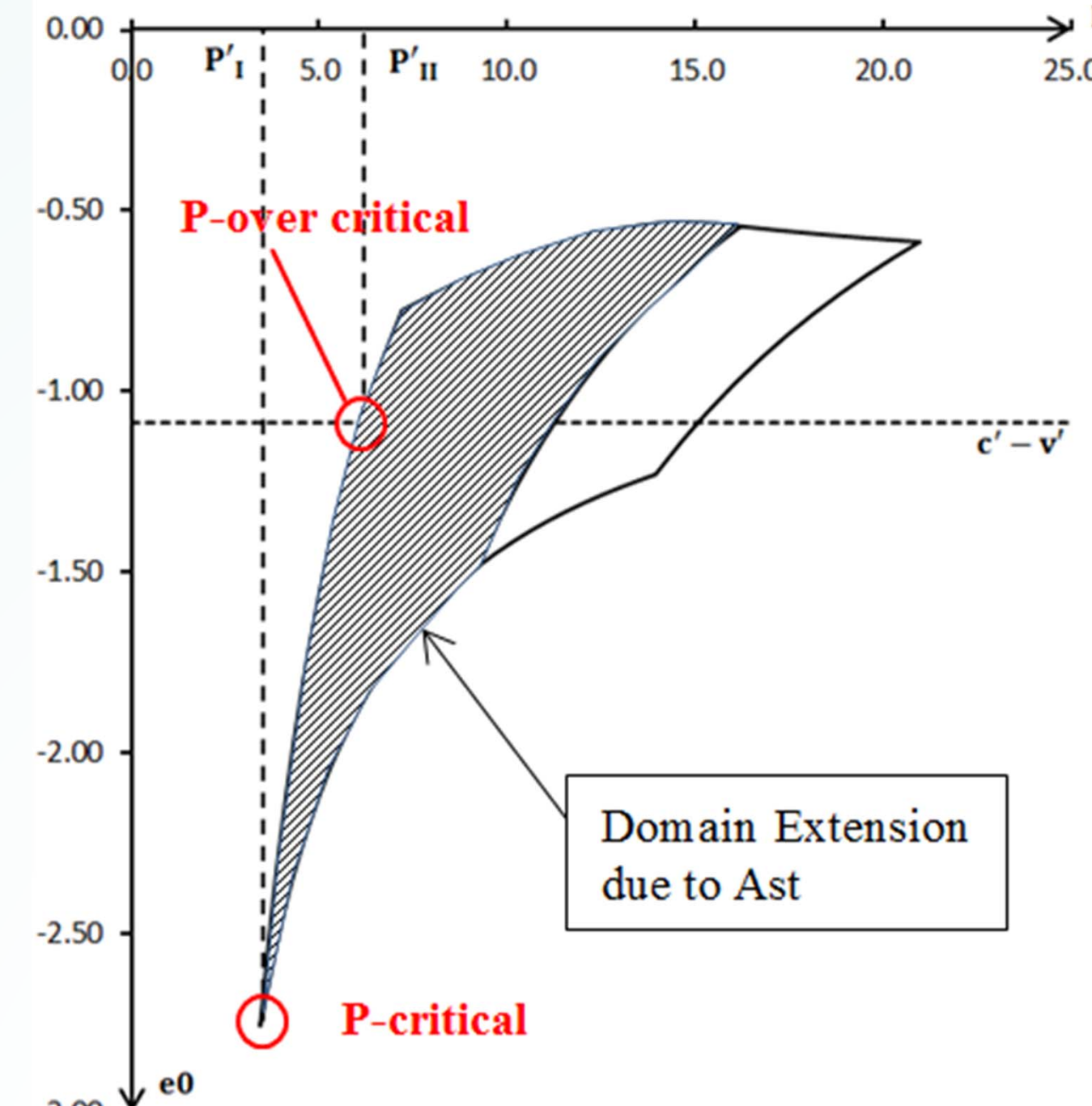
Problem solved without the need of Numerical Methods!!

Rotation due to Prestressing moment formulated Using the "Matrix of Transfer"

$$\delta_i = \int_0^{l_{i+1}} \left(1 - \frac{x}{l_{i+1}}\right) e_0(x) \frac{dx}{EI} + \int_0^{l_i} \frac{x}{l_i} \frac{dx}{EI} = (S_0 - S_1)_{i+1} + S_1$$

Optimization of Partial prestressing force P using Pivot Rule:

Geometry			Stress Limits		
b	2	m	$\bar{\sigma}_1$	-2	Mpa
h	2.5	m	$\bar{\sigma}_2$	24	Mpa
b_w	0.24	m	$\bar{\sigma}_3$	24	Mpa
h_f	0.16	m	$\bar{\sigma}_4$	0	Mpa
b_t	0.8	m	W_k	2	mm
h_t	0.4	m	Material		
h_g	0.2	m	f_{ck}	40	MPa
b_g	0.4	m	$f_{ct,eff}$	3.5	MPa
e_g	0.2	m	E_s	200	GPa
Cover			α_e	5.70	
			Moments		
c	0.2	m	M_{min}	2	MN.m
c'	0.2	m	M_{max}	12	MN.m
c_p	0.04	m			



Results under ELS-car:

	Case 1	Case 2	Case 3	Case 4
$A_{st}(\%)$	0	0.5	1	1.5
$\bar{\sigma}_{st}(Mpa)$	0	197	238	257
P(MN)	12.20	8.03	6.12	4.15

Significate Reduction of P in Partially Prestressed Concrete = 60% for a 1.5% of Ast

Expected Results

- Find the portion of moment to be resisted by Ast for an optimal solution in Partial Prestressed Concrete
- Apply analytical optimization methods for 2 and 3 spans beams
- Develop numerical optimization tool, based on Genetic Algorithm, for a multi span prestressed beam with constant inertia and for a cantilevered bridge with variable inertia



Bibliography

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2. [NIL 77] NILSON A.H., « Flexural Stresses after Cracking in Partially Prestressed Beams », *PCI Journal*, vol. 21, n° 4, 1977, p. 72-81.
3. Z. Aydm and Y. Ayvaz, "Optimum topology and shape design of prestressed concrete bridge girders using genetic algorithms," *Struc Multidisc Optim*, no. 41, pp. 151-162, 2010.
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New Pivot Rule for Fully and Partially Pre-stressed Concrete:

Main Equations to be satisfied by the EN:

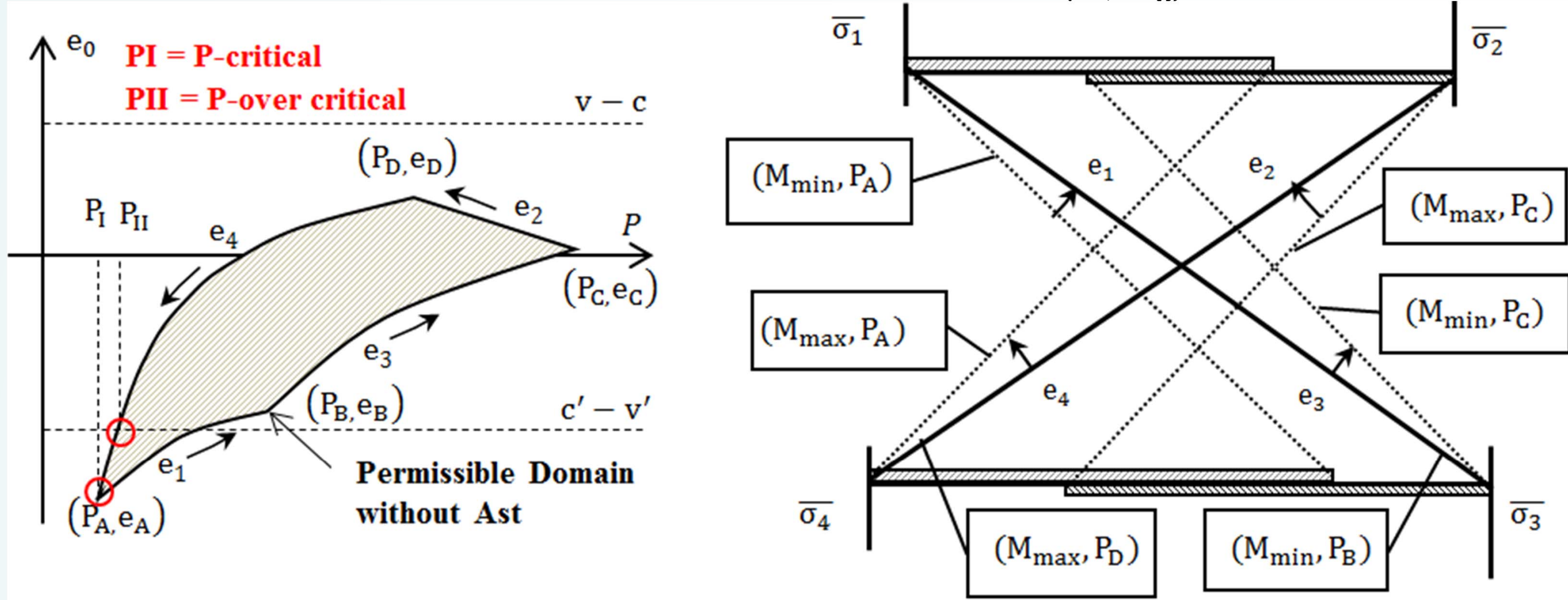
Stress Limitation

Cover Limitation

$$\begin{aligned} \bar{\sigma}_1 &\leq \sigma_{sup}(M_{min}) \leq \sigma_{sup}(M_{max}) \leq \bar{\sigma}_2 \\ \bar{\sigma}_4 &\leq \sigma_{inf}(M_{max}) \leq \sigma_{inf}(M_{min}) \leq \bar{\sigma}_3 \end{aligned}$$

$$-(v' - c') \leq e_0 \leq v - c$$

Permissible domain of (P, e₀):



- Along each Hyperbola e_i , Only **1 constraint** is satisfied
- At Intersection Points, **2 constraints** are satisfied **simultaneously**

Optimization Method

Optimizing an objective function (Cost, P, Ac ...) using either Analytical or Numerical Methods.

$$\text{Minimize } f(X)$$

$$\text{Subject to } g_j(X) < 0$$

$$h_k(X) = 0$$

$$x_{i,lower} < x_i < x_{i,upper}$$

$$f: C_{conc} A_{conc} + C_{Ast} A_{Ast} + C_{Ap} A_{Ap} + \sum w_i \text{Constraint}_i$$

Genetic Algorithm

